FORM HDP-1449 (Based on Form PTO-1449)

PATENT AND TRADEMARK OFFICE JNFORMATION DISCLOSURE CITATION

(Use several sheets if necessary)

Sheet 1 of 1

ATTORNEY DOCKET No.	APPLICATION NO.
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APPLICANT	
Kang Soo SEO et al.	
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U.S. PATENT DOCUMENTS						
Ref. Desig.	Examiner's Initials	Document Number	Date	Name	Class/ Subclas	(If appropriate) ss Filing Date
1.		US 2004/0213552	10/28/2004	KATO		

FOREIGN PATENT DOCUMENTS							
Ref. Desig.	Examiner's Initials	Document Number	Date	Country	Class/ Subclass	Translation Yes	No
1.		JP 2001-052467	02/23/2001	JAPAN		ABST.	
2.		JP 10-154373	06/09/1998	JAPAN		ABST.	
3.		JP 2001-155466	06/08/2001	JAPAN		ABST.	
4.		JP 2002-354424	12/06/2002	JAPAN		ABST.	
5.		JP 2000-004421	01/07/2000	JAPAN		ABST.	

OTHER DOCUMENTS (including Author, Title, Date, Pertinent Pages, etc.)			
Ref. Desig.	Examiner's Initials		
1.		Japanese Office Action dated June 10, 2008	
2.		Japanese Office Action dated June 20, 2008	
3.		United States Office Action dated July 9, 2008	

Examiner:	Date Considered:

value—which is calculated from the measured tare is regarded as representing the tare of the vessel for—purpose of the filling operation, the operation is switched to the second operational mode, and after a given time interval, the filler is again operated in the first operational mode to recalculate the reference value for the tare.

- 3. (Currently amended) A rotary weight filler according to Claim 2—in which, wherein the reference value for the tare is a mean value of measured values.
- 4. (Currently amended) A rotary weight filler according to Claim 2—in which, wherein the reference value of the tare is one of the measured values which appears with a highest frequency.
- 5. (Currently amended) A rotary weight filler according to Claim 2—in which, wherein the reference value for the tare is a median value in a queue of measured values arranged in an ascending or descending order.
- 6. (Currently amended) A rotary weight filler according to Claim 1—in—which, wherein in the first operational mode, the tare of theeach vessel is measured after the attitude of athe vessel supplied has become stabilized and after the weight measuring meansdevice has become stabilized.
- 7. (Currently amended) A rotary weight filler according to Claim 1—in which, wherein in the second operational mode, a fill initiate command signal is delivered to initiate a filling operation after thean attitude of athe vessel supplied has become stabilized.
 - 8. (Currently amended) A rotary weight filler

according to Claim 1—in—which, wherein in the second operational mode, a fill initiate command signal is delivered before thean attitude of the vessel supplied becomes stabilized, and the filling operation is initiated after the attitude of the vessel has become stabilized.

- 9. (New) A rotary weight filler apparatus for receiving and filling vessels with a given quantity of liquid comprising:
 - a revolving body;
- a plurality of filling devices circumferentially spaced and disposed along an outer periphery of the revolving body, each said filling device including a filling valve for opening or closing a corresponding filled liquid passage and a nozzle connected to a corresponding said filling valve for outputting a liquid;
- a plurality of weight measuring devices mounted about the outer periphery of the revolving body, each said weight measuring device corresponding to one of said plurality of filling devices and adapted to receive a vessel thereon; and
- a controller controlling in a first operating mode to open a corresponding said filling valve after a first predetermined time that corresponds to the sum of 1) a vessel stabilization time zone needed for a vessel to stabilize after placement onto the weight measuring device, 2) a load cell stabilization time zone needed for a weight measuring device to stabilize after placement of a vessel thereon, and 3) a tare measuring time zone required for completing measurement of the weight of a vessel by the corresponding weight measuring device, and said controller controlling closing said corresponding filling valve in response to a signal from the corresponding weight measuring device,

wherein the controller determines a reference value for the tare of each corresponding vessel determined during the first operating mode, and

said controller controlling in a second operating mode to open the corresponding said filling valve after a second predetermined time that corresponds to the sum of 1) the vessel stabilization time zone and 2) the load cell stabilization time zone, so that the second operating mode begins initial filling of each corresponding vessel without measuring the tare of a corresponding vessel, said second predetermined time being less than said first predetermined time, and said controller closing the corresponding filling valve in response to a signal from the corresponding weight measuring device.

- 10. (New) The rotary weight filler according to Claim 9, wherein in the second operating mode said filling valve operates at a lower filling rate than in the first operating mode.
- 11. (New) The rotary weight filler according to Claim 9, wherein the controller automatically periodically transfers from the second operating mode to the first operating mode after a second operating mode predetermined time interval to again determine the reference value for the tare of a corresponding vessel.
- 12. (New) The rotary weight filler according to Claim
 11, wherein the reference value for the tare comprises a mean
 value of measured values during a first operating mode time
 interval.
- 13. (New) The rotary weight filler according to Claim
 11, wherein the reference value for the tare comprises the

Serial No. 10/717 262 - Page 7

measured value that occurs the most times during a first operating mode time interval.

14. (New) The rotary weight filler according to Claim 11, wherein the reference value for the tare comprises a median value of the measured values that occur during a first operating mode time interval.